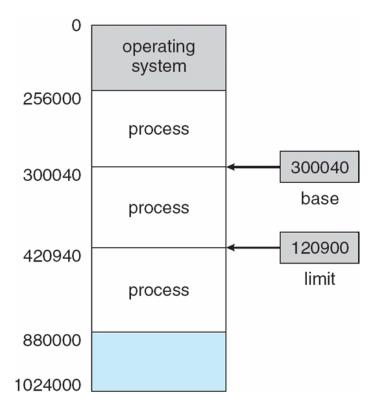
Background

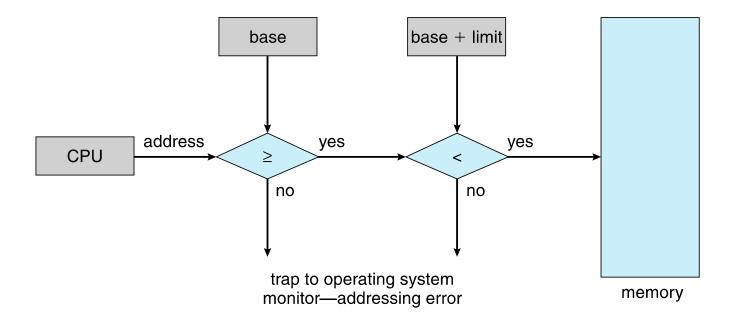
- Program must be brought (from disk) into memory and placed within a process for it to be run
- Main memory and registers are only storage CPU can access directly
- Memory unit only sees a stream of addresses + read requests, or address + data and write requests
- Register access in one CPU clock (or less)
- Main memory can take many cycles, causing a stall
- Cache sits between main memory and CPU registers
- Protection of memory required to ensure correct operation

Base and Limit Registers

- A pair of **base** and **limit registers** define the logical address space
- CPU must check every memory access generated in user mode to be sure it is between base and limit for that user



Hardware Address Protection



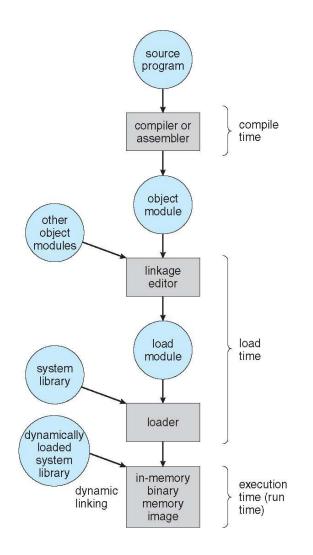
Address Binding

- Programs on disk, ready to be brought into memory to execute form an input queue
 - Without support, must be loaded into address 0000
- Inconvenient to have first user process physical address always at 0000
 - How can it not be?
- Further, addresses represented in different ways at different stages of a program's life
 - Source code addresses usually symbolic
 - Compiled code addresses **bind** to relocatable addresses
 - i.e. "14 bytes from beginning of this module"
 - Linker or loader will bind relocatable addresses to absolute addresses
 - i.e. 74014
 - Each binding maps one address space to another

Binding of Instructions and Data to Memory

- Address binding of instructions and data to memory addresses can happen at three different stages
 - Compile time: If memory location known a priori, absolute code can be generated; must recompile code if starting location changes
 - Load time: Must generate relocatable code if memory location is not known at compile time
 - Execution time: Binding delayed until run time if the process can be moved during its execution from one memory segment to another
 - Need hardware support for address maps (e.g., base and limit registers)

Multistep Processing of a User Program



Logical vs. Physical Address Space

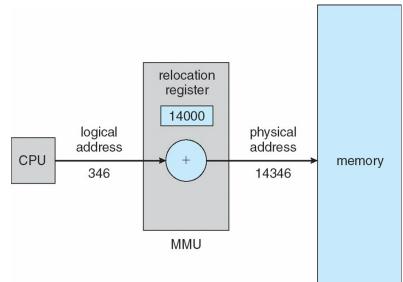
- The concept of a logical address space that is bound to a separate physical address space is central to proper memory management
 - Logical address generated by the CPU; also referred to as virtual address
 - Physical address address seen by the memory unit
- Logical and physical addresses are the same in compiletime and load-time address-binding schemes; logical (virtual) and physical addresses differ in execution-time address-binding scheme
- Logical address space is the set of all logical addresses generated by a program
- Physical address space is the set of all physical addresses generated by a program

Memory-Management Unit (мми)

- Hardware device that at run time maps virtual to physical address
- Many methods possible, covered in the rest of this chapter
- To start, consider simple scheme where the value in the relocation register is added to every address generated by a user process at the time it is sent to memory
 - Base register now called relocation register
 - MS-DOS on Intel 80x86 used 4 relocation registers
- The user program deals with *logical* addresses; it never sees the *real* physical addresses
 - Execution-time binding occurs when reference is made to location in memory
 - Logical address bound to physical addresses

Dynamic relocation using a relocation register

- Routine is not loaded until it is called
- Better memory-space utilization; unused routine is never loaded
- All routines kept on disk in relocatable load format
- Useful when large amounts of code are needed to handle infrequently occurring cases
- No special support from the operating system is required
 - Implemented through program design
 - OS can help by providing libraries to implement dynamic loading



Dynamic Linking

- Static linking system libraries and program code combined by the loader into the binary program image
- Dynamic linking –linking postponed until execution time
- Small piece of code, stub, used to locate the appropriate memory-resident library routine
- Stub replaces itself with the address of the routine, and executes the routine
- Operating system checks if routine is in processes' memory address
 - If not in address space, add to address space
- Dynamic linking is particularly useful for libraries
- System also known as shared libraries
- Consider applicability to patching system libraries
 - Versioning may be needed

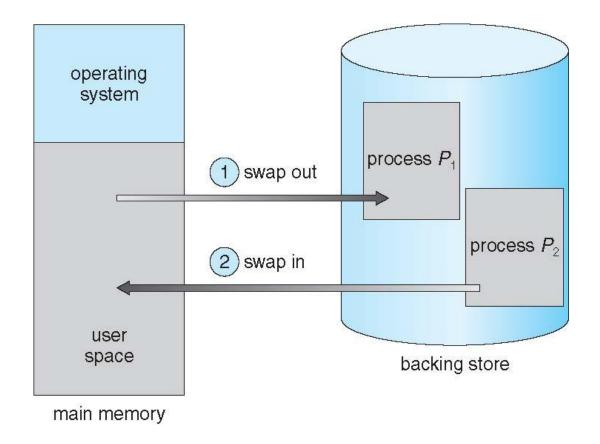
Swapping

- A process can be **swapped** temporarily out of memory to a backing store, and then brought back into memory for continued execution
 - Total physical memory space of processes can exceed physical memory
- **Backing store** fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images
- Roll out, roll in swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed
- Major part of swap time is transfer time; total transfer time is directly proportional to the amount of memory swapped
- System maintains a **ready queue** of ready-to-run processes which have memory images on disk

Swapping (Cont.)

- Does the swapped out process need to swap back in to same physical addresses?
- Depends on address binding method
 - Plus consider pending I/O to / from process memory space
- Modified versions of swapping are found on many systems (i.e., UNIX, Linux, and Windows)
 - Swapping normally disabled
 - Started if more than threshold amount of memory allocated
 - Disabled again once memory demand reduced below threshold

Schematic View of Swapping



Context Switch Time including Swapping

- If next processes to be put on CPU is not in memory, need to swap out a process and swap in target process
- Context switch time can then be very high
- 100MB process swapping to hard disk with transfer rate of 50MB/sec
 - Swap out time of 2000 ms
 - Plus swap in of same sized process
 - Total context switch swapping component time of 4000ms (4 seconds)
- Can reduce if reduce size of memory swapped by knowing how much memory really being used
 - System calls to inform OS of memory use via
 request_memory() and release_memory()

Context Switch Time and Swapping (Cont.)

- Other constraints as well on swapping
 - Pending I/O can't swap out as I/O would occur to wrong process
 - Or always transfer I/O to kernel space, then to I/O device
 - Known as **double buffering**, adds overhead
- Standard swapping not used in modern operating systems
 - But modified version common
 - Swap only when free memory extremely low

Swapping on Mobile Systems

- Not typically supported
 - Flash memory based
 - Small amount of space
 - Limited number of write cycles
 - Poor throughput between flash memory and CPU on mobile platform
- Instead use other methods to free memory if low
 - iOS *asks* apps to voluntarily relinquish allocated memory
 - Read-only data thrown out and reloaded from flash if needed
 - Failure to free can result in termination
 - Android terminates apps if low free memory, but first writes application state to flash for fast restart
 - Both OSes support paging as discussed below

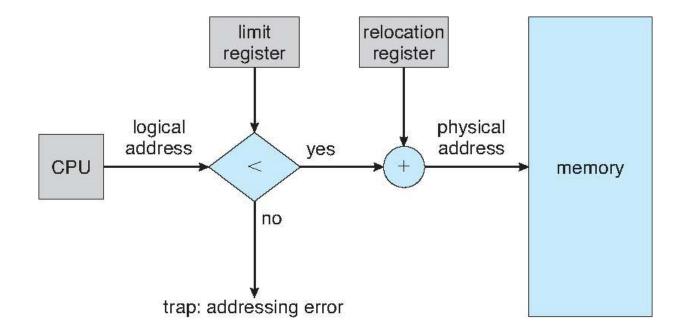
Contiguous Allocation

- Main memory must support both OS and user processes
- Limited resource, must allocate efficiently
- Contiguous allocation is one early method
- Main memory usually into two partitions:
 - Resident operating system, usually held in low memory with interrupt vector
 - User processes then held in high memory
 - Each process contained in single contiguous section of memory

Contiguous Allocation (Cont.)

- Relocation registers used to protect user processes from each other, and from changing operating-system code and data
 - Base register contains value of smallest physical address
 - Limit register contains range of logical addresses – each logical address must be less than the limit register
 - MMU maps logical address *dynamically*
 - Can then allow actions such as kernel code being transient and kernel changing size

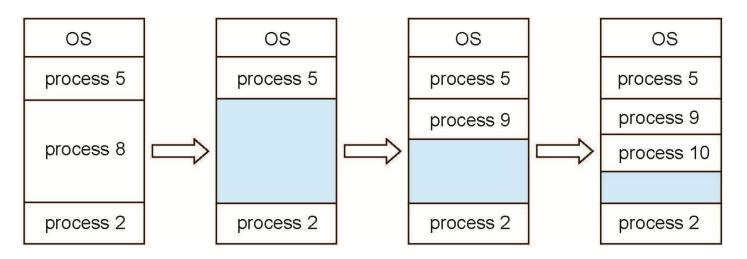
Hardware Support for Relocation and Limit Registers



Multiple-partition allocation

• Multiple-partition allocation

- Degree of multiprogramming limited by number of partitions
- Variable-partition sizes for efficiency (sized to a given process' needs)
- Hole block of available memory; holes of various size are scattered throughout memory
- When a process arrives, it is allocated memory from a hole large enough to accommodate it
- Process exiting frees its partition, adjacent free partitions combined
- Operating system maintains information about:
 a) allocated partitions
 b) free partitions (hole)



Dynamic Storage-Allocation Problem

How to satisfy a request of size *n* from a list of free holes?

- First-fit: Allocate the *first* hole that is big enough
- **Best-fit**: Allocate the *smallest* hole that is big enough; must search entire list, unless ordered by size
 - Produces the smallest leftover hole
- Worst-fit: Allocate the *largest* hole; must also search entire list
 - Produces the largest leftover hole

First-fit and best-fit better than worst-fit in terms of speed and storage utilization

Fragmentation

- External Fragmentation total memory space exists to satisfy a request, but it is not contiguous
- Internal Fragmentation allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used
- First fit analysis reveals that given N blocks allocated, 0.5 N blocks lost to fragmentation
 - 1/3 may be unusable -> 50-percent rule

Fragmentation (Cont.)

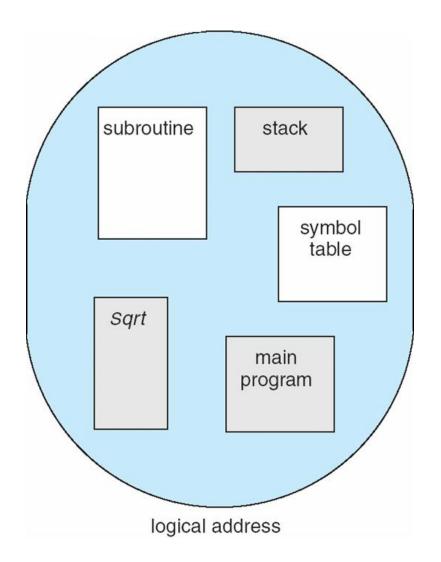
- Reduce external fragmentation by compaction
 - Shuffle memory contents to place all free memory together in one large block
 - Compaction is possible *only* if relocation is dynamic, and is done at execution time
 - I/O problem
 - Latch job in memory while it is involved in I/O
 - Do I/O only into OS buffers
- Now consider that backing store has same fragmentation problems

Segmentation

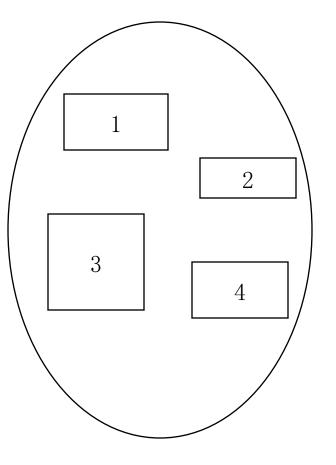
- Memory-management scheme that supports user view of memory
- A program is a collection of segments
 - A segment is a logical unit such as:

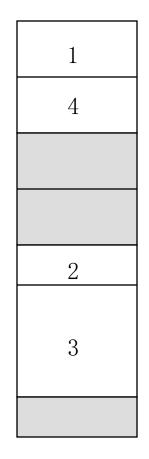
main program procedure function method object local variables, global variables common block stack symbol table arrays

User's View of a Program



Logical View of Segmentation





user space

physical memory space

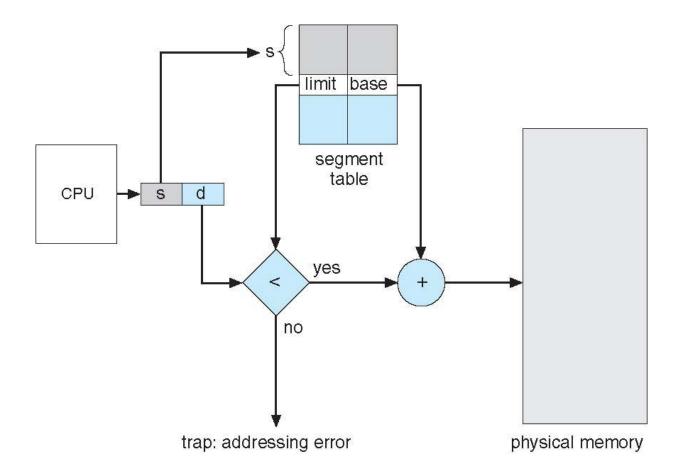
Segmentation Architecture

- Logical address consists of a two tuple: <segment-number, offset>,
- Segment table maps two-dimensional physical addresses; each table entry has:
 - base contains the starting physical address where the segments reside in memory
 - limit specifies the length of the segment
- Segment-table base register (STBR) points to the segment table's location in memory
- Segment-table length register (STLR) indicates number of segments used by a program; segment number s is legal if s < STLR

Segmentation Architecture (Cont.)

- Protection
 - With each entry in segment table associate:
 - validation bit = $0 \Rightarrow$ illegal segment
 - read/write/execute privileges
- Protection bits associated with segments; code sharing occurs at segment level
- Since segments vary in length, memory allocation is a dynamic storage-allocation problem
- A segmentation example is shown in the following diagram

Segmentation Hardware



Paging

- Physical address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available
 - Avoids external fragmentation
 - Avoids problem of varying sized memory chunks
- Divide physical memory into fixed-sized blocks called **frames**
 - Size is power of 2, between 512 bytes and 16 Mbytes
- Divide logical memory into blocks of same size called pages
- Keep track of all free frames
- To run a program of size *N* pages, need to find *N* free frames and load program
- Set up a page table to translate logical to physical addresses
- Backing store likewise split into pages
- Still have Internal fragmentation

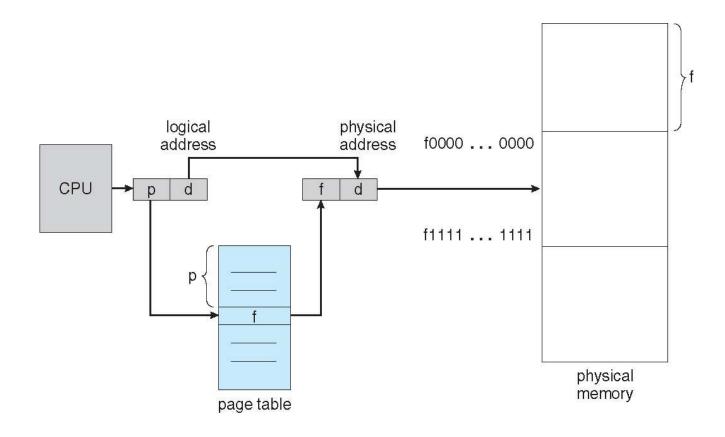
Address Translation Scheme

- Address generated by CPU is divided into:
 - Page number (p) used as an index into a page table which contains base address of each page in physical memory
 - Page offset (d) combined with base address to define the physical memory address that is sent to the memory unit

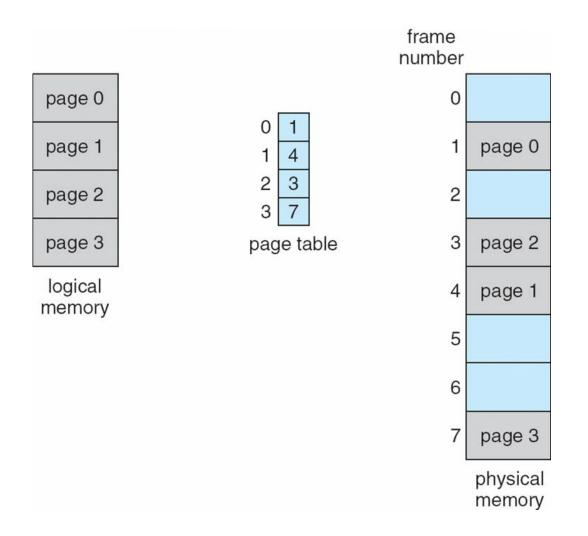
page number	page offset
р	d
m -n	n

- For given logical address space 2^m and page size 2ⁿ

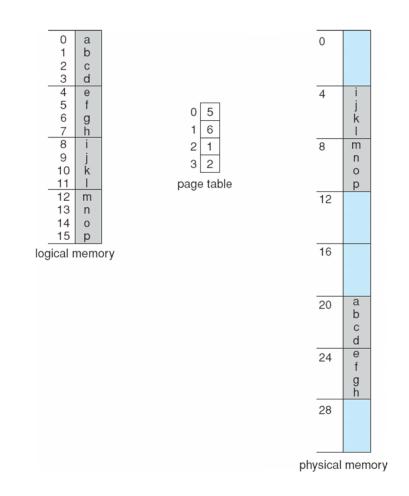
Paging Hardware



Paging Model of Logical and Physical Memory



Paging Example

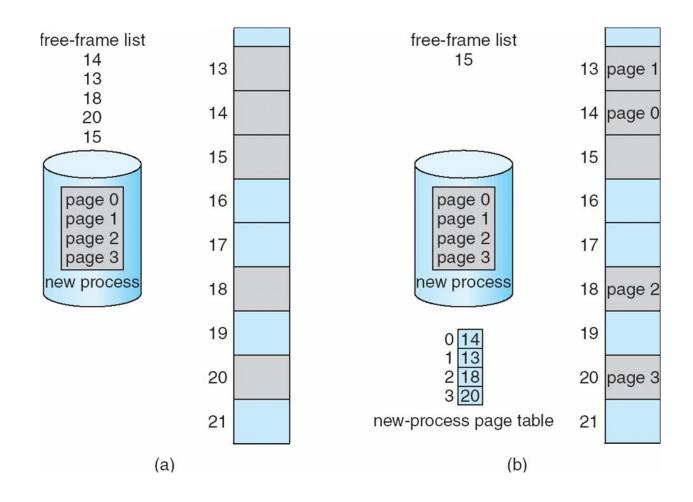


n=2 and n=4 32-byte memory and 4-byte pages

Paging (Cont.)

- Calculating internal fragmentation
 - Page size = 2,048 bytes
 - Process size = 72,766 bytes
 - 35 pages + 1,086 bytes
 - Internal fragmentation of 2,048 1,086 = 962 bytes
 - Worst case fragmentation = 1 frame 1 byte
 - On average fragmentation = 1 / 2 frame size
 - So small frame sizes desirable?
 - But each page table entry takes memory to track
 - Page sizes growing over time
 - Solaris supports two page sizes 8 KB and 4 MB
- Process view and physical memory now very different
- By implementation process can only access its own memory

Free Frames



Before allocation

After allocation

Implementation of Page Table

- Page table is kept in main memory
- Page-table base register (PTBR) points to the page table
- Page-table length register (PTLR) indicates size of the page table
- In this scheme every data/instruction access requires two memory accesses
 - One for the page table and one for the data / instruction
- The two memory access problem can be solved by the use of a special fast-lookup hardware cache called associative memory or translation look-aside buffers (TLBs)

Implementation of Page Table (Cont.)

Some TLBs store address-space identifiers

 (ASIDs) in each TLB entry – uniquely identifies
 each process to provide address-space
 protection for that process

Otherwise need to flush at every context switch

- TLBs typically small (64 to 1,024 entries)
- On a TLB miss, value is loaded into the TLB for faster access next time
 - Replacement policies must be considered
 - Some entries can be wired down for permanent fast access

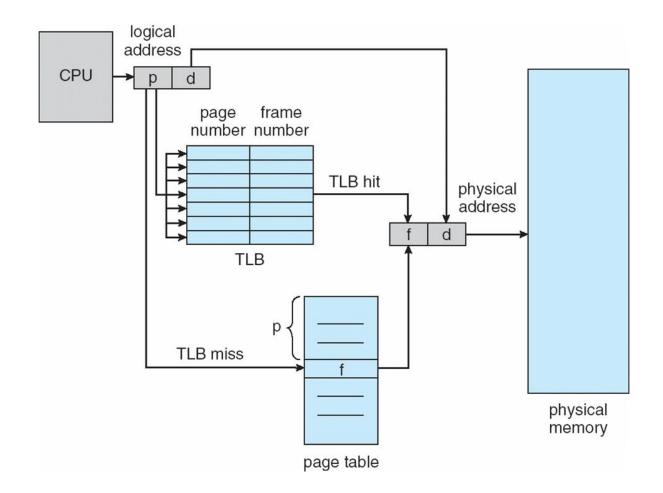
Associative Memory

• Associative memory – parallel search



- Address translation (p, d)
 - If p is in associative register, get frame # out
 - Otherwise get frame # from page table in memory

Paging Hardware With TLB



Effective Access Time

- Associative Lookup = ε time unit
 - Can be < 10% of memory access time
- Hit ratio = α
 - Hit ratio percentage of times that a page number is found in the associative registers; ratio related to number of associative registers
- Consider α = 80%, ϵ = 20ns for TLB search, 100ns for memory access
- Effective Access Time (EAT)

EAT =
$$(1 + \varepsilon) \alpha + (2 + \varepsilon)(1 - \alpha)$$

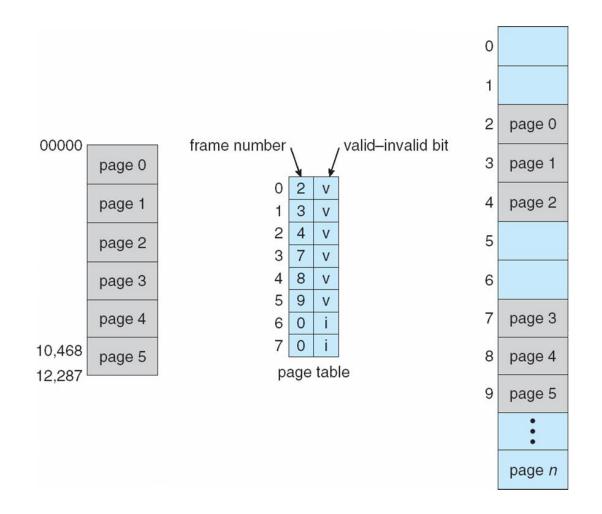
= 2 + $\varepsilon - \alpha$

- Consider α = 80%, ϵ = 20ns for TLB search, 100ns for memory access
 - EAT = 0.80 x 100 + 0.20 x 200 = 120ns
- Consider more realistic hit ratio -> α = 99%, ϵ = 20ns for TLB search, 100ns for memory access
 - EAT = 0.99 x 100 + 0.01 x 200 = 101ns

Memory Protection

- Memory protection implemented by associating protection bit with each frame to indicate if read-only or read-write access is allowed
 - Can also add more bits to indicate page execute-only, and so on
- Valid-invalid bit attached to each entry in the page table:
 - "valid" indicates that the associated page is in the process' logical address space, and is thus a legal page
 - "invalid" indicates that the page is not in the process' logical address space
 - Or use page-table length register (PTLR)
- Any violations result in a trap to the kernel

Valid (v) or Invalid (i) Bit In A Page Table

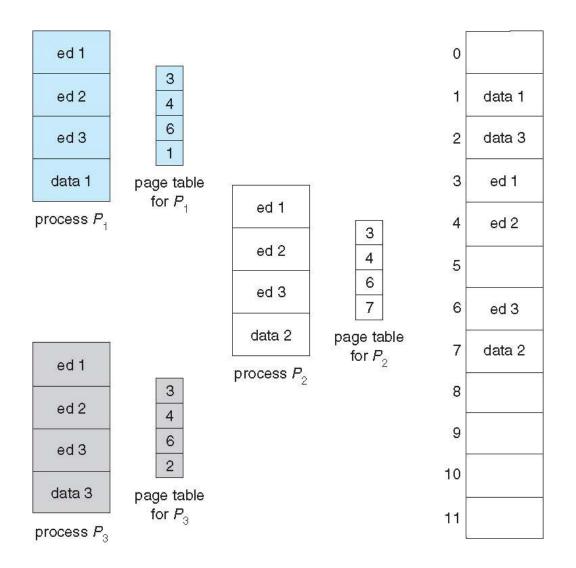


Shared Pages

• Shared code

- One copy of read-only (reentrant) code shared among processes (i.e., text editors, compilers, window systems)
- Similar to multiple threads sharing the same process space
- Also useful for inter-process communication if sharing of read-write pages is allowed
- Private code and data
 - Each process keeps a separate copy of the code and data
 - The pages for the private code and data can appear anywhere in the logical address space

Shared Pages Example



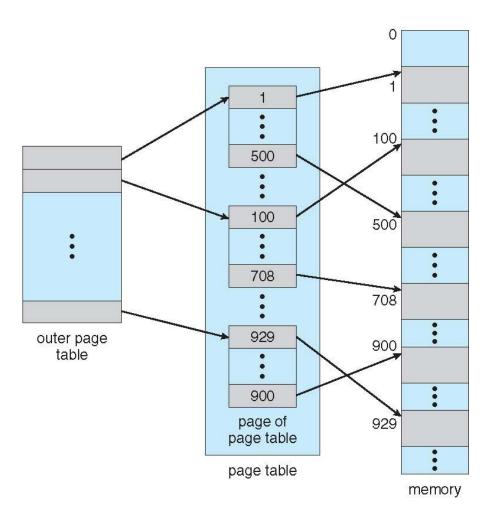
Structure of the Page Table

- Memory structures for paging can get huge using straight-forward methods
 - Consider a 32-bit logical address space as on modern computers
 - Page size of 4 KB (2^{12})
 - Page table would have 1 million entries $(2^{32} / 2^{12})$
 - If each entry is 4 bytes -> 4 MB of physical address space / memory for page table alone
 - That amount of memory used to cost a lot
 - Don't want to allocate that contiguously in main memory
- Hierarchical Paging
- Hashed Page Tables
- Inverted Page Tables

Hierarchical Page Tables

- Break up the logical address space into multiple page tables
- A simple technique is a two-level page table
- We then page the page table

Two-Level Page-Table Scheme



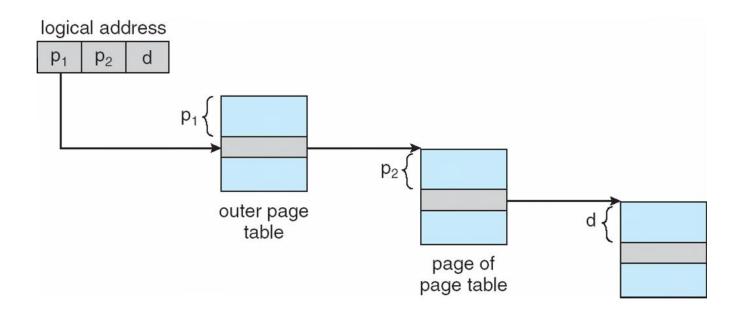
Two-Level Paging Example

- A logical address (on 32-bit machine with 1K page size) is divided into:
 - a page number consisting of 22 bits
 - a page offset consisting of 10 bits
- Since the page table is paged, the page number is further divided into:
 - a 12-bit page number
 - a 10-bit page offset
- Thus, a logical address is as follows:

page number		page offset
<i>p</i> ₁	<i>p</i> ₂	d
12	10	10

- where p_1 is an index into the outer page table, and p_2 is the displacement within the page of the inner page table
- Known as forward-mapped page table

Address-Translation Scheme



64-bit Logical Address Space

- Even two-level paging scheme not sufficient
- If page size is 4 KB (2¹²)
 - Then page table has 2⁵² entries
 - If two level scheme, inner page tables could be 2¹⁰ 4-byte entries
 - Address would look like

outer	page	inner page	page offset
	р ₁	<i>p</i> ₂	d
	42	10	12

- Outer page table has 2⁴² entries or 2⁴⁴ bytes
- One solution is to add a 2nd outer page table
- But in the following example the 2nd outer page table is still 2³⁴ bytes in size
 - And possibly 4 memory access to get to one physical memory location

Three-level Paging Scheme

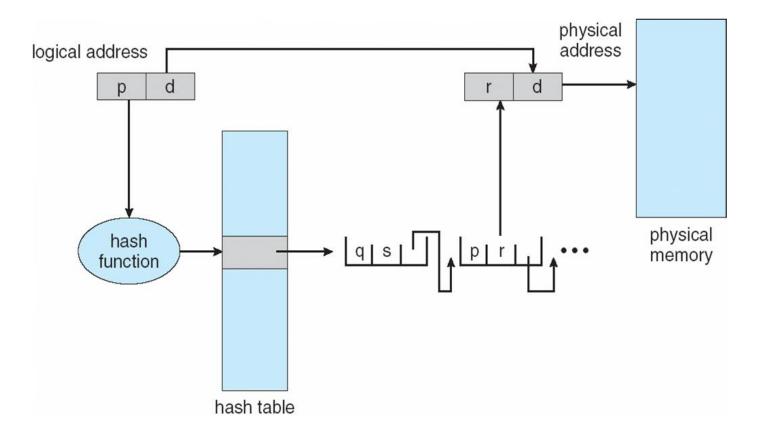
outer page	inner page	offset
p_1	p_2	d
42	10	12

2nd outer page	outer page	inner page	offset
p_1	p_2	<i>p</i> ₃	d
32	10	10	12

Hashed Page Tables

- Common in address spaces > 32 bits
- The virtual page number is hashed into a page table
 - This page table contains a chain of elements hashing to the same location
- Each element contains (1) the virtual page number (2) the value of the mapped page frame (3) a pointer to the next element
- Virtual page numbers are compared in this chain searching for a match
 - If a match is found, the corresponding physical frame is extracted
- Variation for 64-bit addresses is **clustered page tables**
 - Similar to hashed but each entry refers to several pages (such as 16) rather than 1
 - Especially useful for sparse address spaces (where memory references are non-contiguous and scattered)

Hashed Page Table



Inverted Page Table

- Rather than each process having a page table and keeping track of all possible logical pages, track all physical pages
- One entry for each real page of memory
- Entry consists of the virtual address of the page stored in that real memory location, with information about the process that owns that page
- Decreases memory needed to store each page table, but increases time needed to search the table when a page reference occurs
- Use hash table to limit the search to one or at most a few page-table entries
 - TLB can accelerate access
- But how to implement shared memory?
 - One mapping of a virtual address to the shared physical address

Inverted Page Table Architecture

