## Numerical Methods

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## System of linear equations

We consider the problem of finding numerically $n$ scalars $x_{1}, x_{2}, \ldots, x_{n}$ which satisfy the conditions

$$
\left(\begin{array}{ccccc}
a_{11} x_{1} & + & a_{12} x_{2} & + & \cdots \\
a_{22} x_{2} & + & \cdots & + & a_{1 n} x_{n} \\
a_{21} x_{1} x_{n} & + & =\left(\begin{array}{c}
b_{1} \\
b_{2} \\
\vdots
\end{array}\right. & \vdots & \\
\vdots & \vdots \\
a_{n 1} x_{1} & + & a_{n 2} x_{2} & + & \cdots \\
\vdots \\
b_{n}
\end{array}\right)
$$

where $b_{1}, b_{2}, \cdots, b_{m}$ and $a_{i j}, 1 \leq i \leq \stackrel{n}{m}, 1 \leq j \leq \overline{n \text { are given real numbers. The system }}$ (1) is known as a system of $n$ linear equation in $n$ unknowns

We can write the system (1) as follows:

Where, $A=$

$A$ is called the

By the virtue of linear algebra it is well known that the above system has a unique solution if and only if $A^{-1}$ exists and this is true if and only if $\operatorname{det} A \neq 0$.

Now in the entire chapter we assume that $\operatorname{det} A \neq 0$ so that unique solution exists, then our aim will be to compute the $n$ unknown vector $x$ up to a desired degree of accuracy.

Broadly there are two types numerical methods are available to compute such system, namely:

The direct or exact methods, such as Cramer's rule, Gauss's elimination method etc.

The iterative methods such as Gauss Jacobi method, Gauss Seidel method etc.


Let us assume that the system (1) has unique solution and consider the augmented matrix $[A \mid b]$ of the system (1).

Now, using elementary row transformations, Gauss elimination method reduces the matrix $A$ in the augmented matrix to an upper triangular form, such that $[A \mid b] \longrightarrow[U \mid c]$. Then by back substitution we obtain the solution. To do this we proceed as follows. First, we write


$$
\begin{equation*}
a_{i j}^{(1)}=a_{i j}, \quad b_{i}^{(1)}=b_{i}, \quad i, j=1,2, \cdots, n \tag{2}
\end{equation*}
$$



Let $a_{11}^{(1)} \neq 0$, multinly the first equation of (1) by $m_{i 1}=-a_{i 11}^{(1)} / a_{11}^{(1)}$ and then add to the $i$ th equation when $x_{1}$ is eliminated from that equation, where $i=2,3, \cdots, n$, which gives the following equivalent system of equations


Again assume, $a_{22}^{(2)} \neq 0$. We note that the set of equation (3) except the first one is a system of $n-1$ linear equations in the $n-1$ unknowns $x_{2}, x_{3}, \cdots, x_{n}$, and then applying the same elimination procedure to this system $x_{2}$ is eliminated from the last $n-2$ equations. So, we have equivalent system as follows,

$$
\frac{a_{11}^{(1)} x_{1}+a_{12}^{(1)} x_{2}+a_{13}^{(1)} x_{3}+\cdots+a_{1 n}^{(1)} x_{n}=b_{1}^{(1)}}{a_{22}^{(2)} x_{2}+a_{23}^{(2)} x_{3}+\cdots+a_{2 n}^{(2)} x_{n}=b_{2}^{(2)}}
$$

$$
\begin{equation*}
\frac{a_{33}^{(3)} x_{3}+\cdots+a_{3 n}^{(3)} x_{n}=b_{3}^{(3)}}{a_{n 3}^{(3)} x_{3}+\cdots+a_{n n}^{(3)} x_{n}=b_{n}^{(3)}} \tag{5}
\end{equation*}
$$

where

$$
\begin{align*}
& m_{i 2}=-a_{i 2}^{(2)} / a_{22}^{(2)} \\
& a_{i j}^{(3)}=a_{i j}^{(2)}+m_{i 2} a_{2 j}, \quad b_{i}^{(3)}=b_{i}^{(2)}+m_{i 2} b_{2}^{(2)}, \quad i, j=3,4, \cdots, n \tag{6}
\end{align*}
$$

Continuing this process repeatedly, we obtain the following equivalent system of equations at the $n-1$ th step as
where

$$
\begin{align*}
m_{i k}= & -a_{i k}^{(k)} / a_{k k}^{(k)} \\
a_{i j}^{(k+1)}= & a_{i j}^{(k)}+m_{i k} a_{k j}, b_{i}^{(k+1)}=b_{i}^{(k)}+m_{i k} b_{k}^{(k)} \\
& \quad i, j=k+1, k+2, \cdots, n ; k=1,2, \cdots, n . \tag{8}
\end{align*}
$$

The leading coefficients of the above system of equations (7) $a_{11}^{(1)}, a_{22}^{(2)}, \cdots, a_{n n}^{(n)}$, which are nonzero by assumption, are known as the pivots and the corresponding equations are called the pivotal equations.
We observe that the coefficient matrix of (7) is

$$
U=\left[\begin{array}{ccccc}
a_{11}^{(1)} & a_{12}^{(1)} & a_{13}^{(1)} & \ldots & a_{1 n}^{(1)}  \tag{9}\\
0 & a_{22}^{(2)} & a_{23}^{(2)} & \cdots & a_{2 n}^{(2)} \\
0 & 0 & \frac{a_{33}^{(3)}}{0} & \cdots & a_{3 n}^{(3)} \\
\cdots & \cdots & \cdots & \cdots & \cdots \\
0 & 0 & 0 & \cdots & a_{n n}^{(n)}
\end{array}\right]
$$

an upper triangular matrix. Hence, the value of its determinat is

$$
\begin{equation*}
\operatorname{det} U=a_{11}^{(1)} a_{22}^{(2)} a_{33}^{(3)} \cdots a_{n n}^{(n)} \tag{10}
\end{equation*}
$$

which follows that $\operatorname{det} U \neq 0$ so that the system (7) has a unique solution.
Now the upper triangular system (7) can be easily solved as follows.
From the last equation we get $x_{n}=b_{n}^{(n)} / a_{n n}^{(n)}$; then we substitute this value of $x_{n}$ in the last but one equation, we get the value of $x_{n-1}$, and then we substitute these values of $x_{n}$ and $x_{n-1}$ in the last but two equation and we compute $x_{n-2}$; and so on, finally we get $x_{1}$.

This process of solving an upper triangular system of linear equations is generally called back substitution.

## Examples on Gauss's elimination method

i). Deduce the upper triangular matrix form the following matrix-


$$
\left[\begin{array}{ccc}
4 & 1 & 1 \\
1, & 4 & -2 \\
3 & 2 & -4
\end{array}\right]
$$

ii). Solve the following system of equations

$$
\begin{aligned}
x+y-z & =2 \\
2 x+3 y+5 z & =-3 \\
3 x+2 y-3 z & =6
\end{aligned}
$$

by the Gauss elimination method.

